

# General announcements

- Check out lab covers outside the classroom door for amusement, inspiration, etc.
- This is a short unit! Next test is next Thursday, 9/14 for the B folks and Friday, 9/15 for the C folks
  - It will cover:
    - Vectors vs scalars      Graphical and mathematical vector manipulation
    - 2D kinematics (i.e. projectile motion!)
- 2 labs this unit:
  - Tilted Table lab: we collected data yesterday—
  - To Catch a Ball lab: “run and shoot” – you predict, and we do in class. No formal write up. This will be done this Friday.

# Vectors and scalars

- **SCALARS** have only magnitude

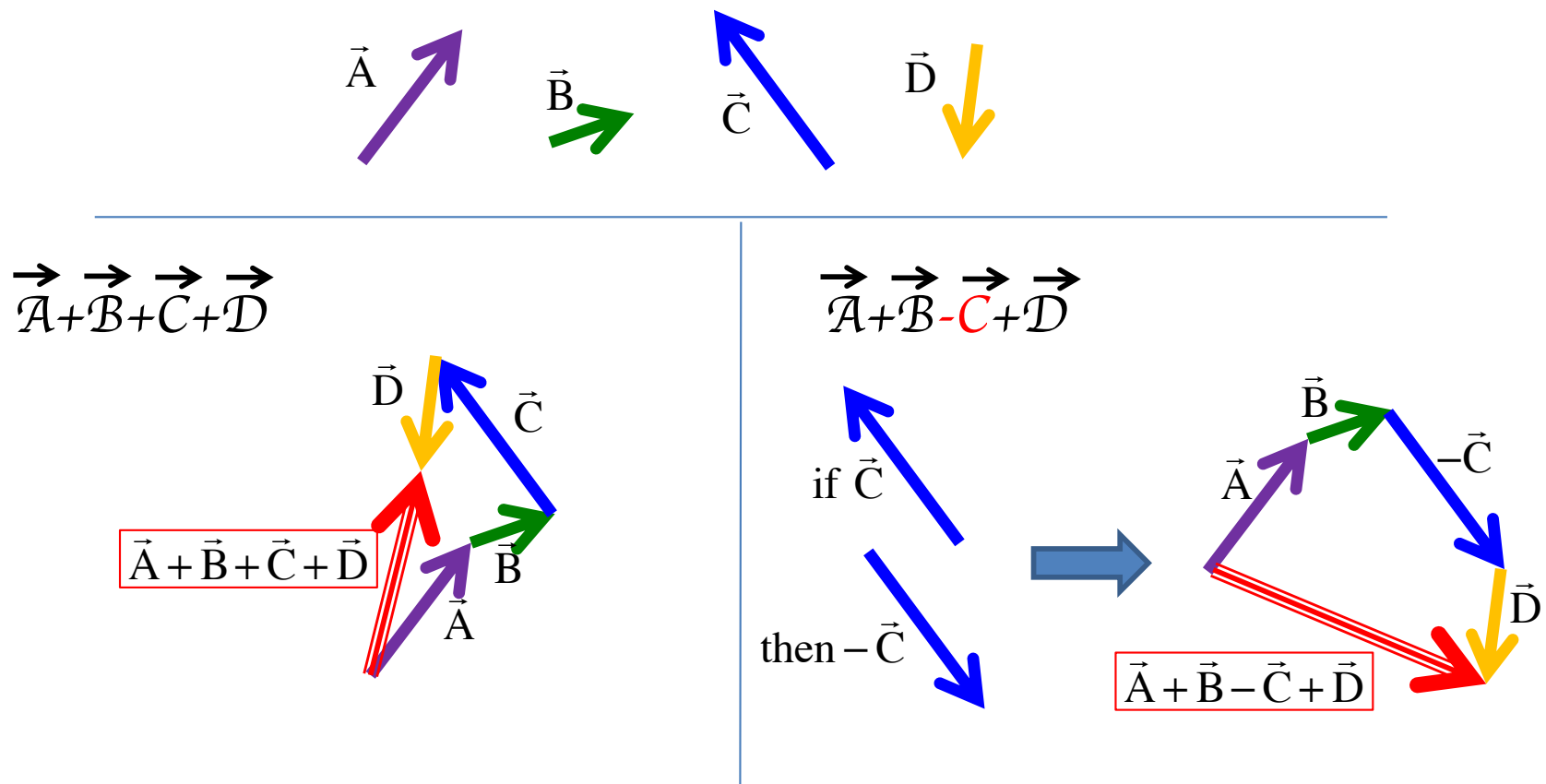
$T = 78^\circ\text{F}$  (not 78 degrees *down* or *up*, just 78 degrees—just a relative measure of the average amount of kinetic energy per molecule of air)

- **VECTORS** have a magnitude AND a direction

There are two ways to deal with vectors, graphically and in conjunction with a coordinate axis. We'll start with the graphical approach first.

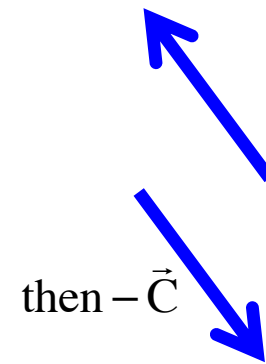
# Graphical addition of vectors

This is also known as the “tip to tail” method

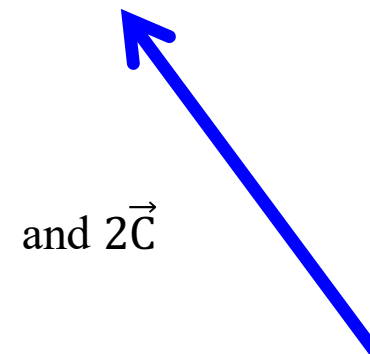
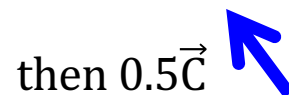
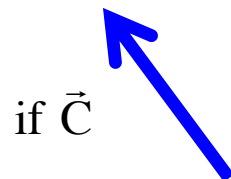


# Vector odds n' ends

- *Subtracting* a vector just means reversing its direction  $180^\circ$  without changing its magnitude, as we saw on the previous slide.



- You can also change the magnitude of a vector by scaling it!



# Graphical manipulation

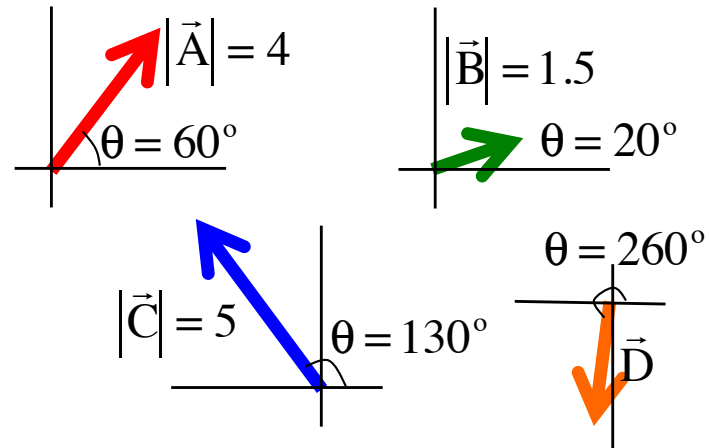
$$\vec{A} = 4 \angle 60^\circ$$

$$\vec{B} = 1.5 \angle 20^\circ$$

$$\vec{C} = 5 \angle 130^\circ$$

$$\vec{D} = 3 \angle 260^\circ$$

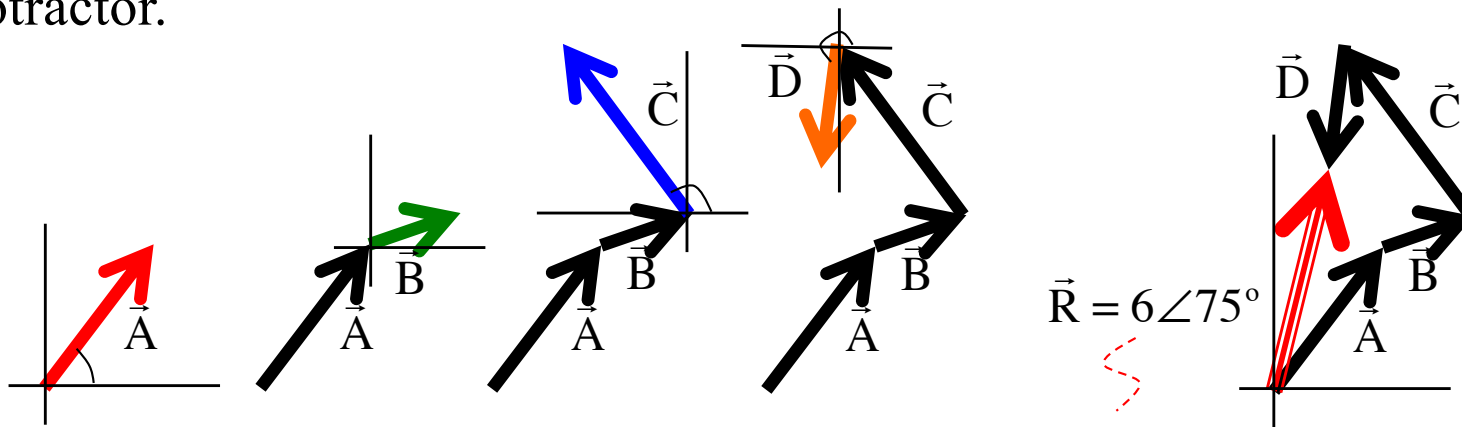
individual  
vectors:



- *Given* information about the magnitude (length) and orientation (angle) of each vector, use a **ruler** and a **protractor** to draw vectors to scale.

# Graphical manipulation

- *To* graphically add vectors, draw each scaled vector **tip to tail** in order, being careful to keep lengths and orientations accurate.
- *Draw* the **resultant vector** from the **starting point (tail)** of the first vector to the **ending point (tip)** of the last vector. Measure with ruler and protractor.



(using **cm. stick** and **protractor**)

# VECTORS

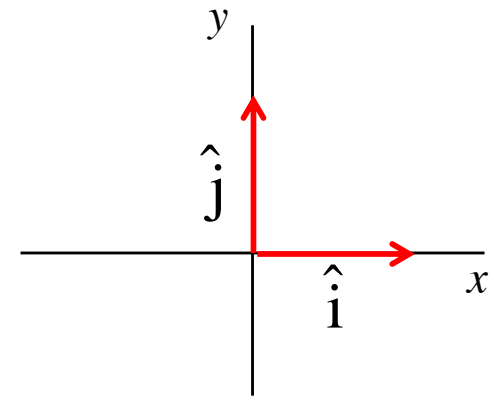
**Vectors** (defined in *polar notation*)

$$\vec{F} = (8 \text{ nt}) \angle 125^\circ$$

(a force whose magnitude is 8 newtons oriented at an angle of 125 degrees relative to the +x-axis)

**Vectors** (defined in *unit vector notation*)

A vector with magnitude ONE defined to be in the **x-direction** is called a **UNIT VECTOR in the x-direction**. Its symbol is  $\hat{i}$  (pronounced “i-hat”). The unit vector in the y-direction is  $\hat{j}$ .



A vector framed in Cartesian coordinates in *unit vector notation* might look like:

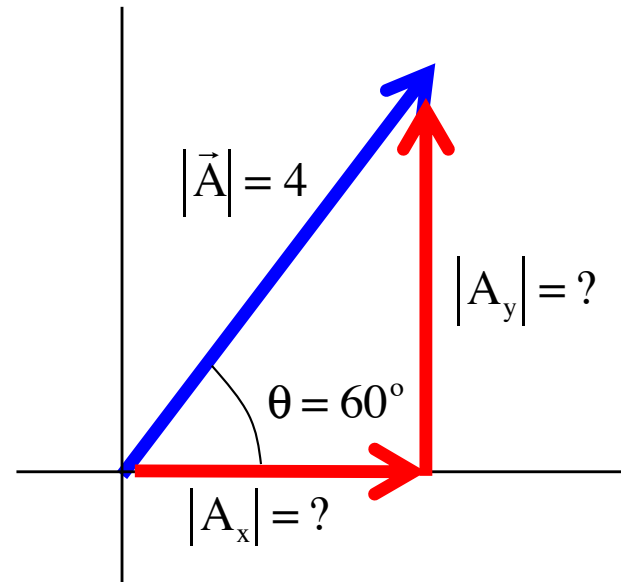
$$\vec{v} = (3 \text{ m/s})\hat{i} + (4 \text{ m/s})(-\hat{j})$$

(this is really the addition of a mini-vector of magnitude 3 m/s in the x-direction and a mini-vector of magnitude 4 in the minus y-direction)

# Vector conversions

- How do we go from polar to unit vector notation?
  - Example 1:

$\vec{A} = 4 \angle 60^\circ$  to unit vector



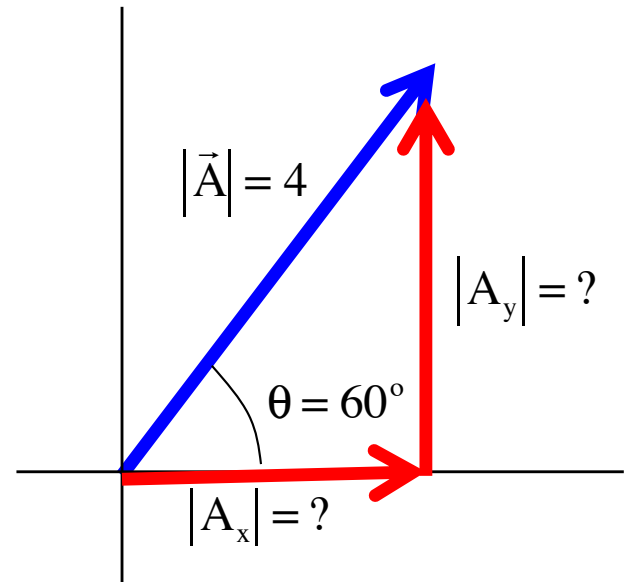


# Vector conversions

- *How* do we go from polar to unit vector notation?
  - Example 1:

$\vec{A} = 4 \angle 60^\circ$  to unit vector

$$\begin{aligned}\vec{A} &= A_x \hat{i} + A_y \hat{j} \\ &= (|\vec{A}| \cos \theta) \hat{i} + (|\vec{A}| \sin \theta) \hat{j} \\ &= (4 \cos 60^\circ) \hat{i} + (4 \sin 60^\circ) \hat{j} \\ &= 2\hat{i} + 3.46\hat{j}\end{aligned}$$

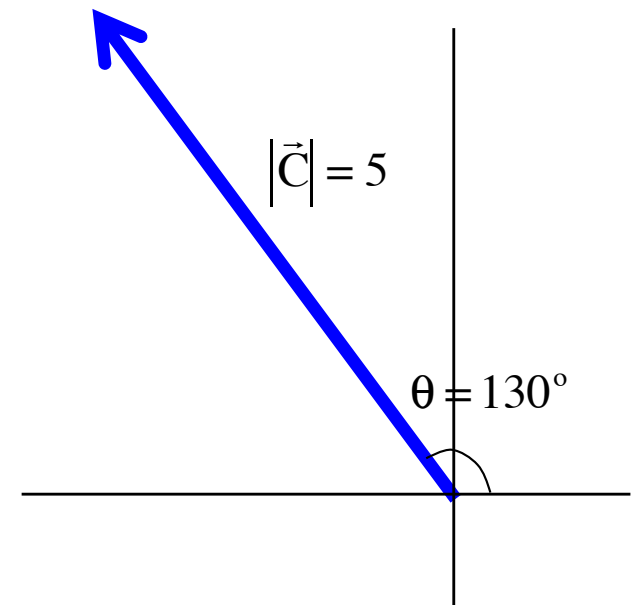


# Vector conversions

- *How* do we go from polar to unit vector notation?
  - Example 2:

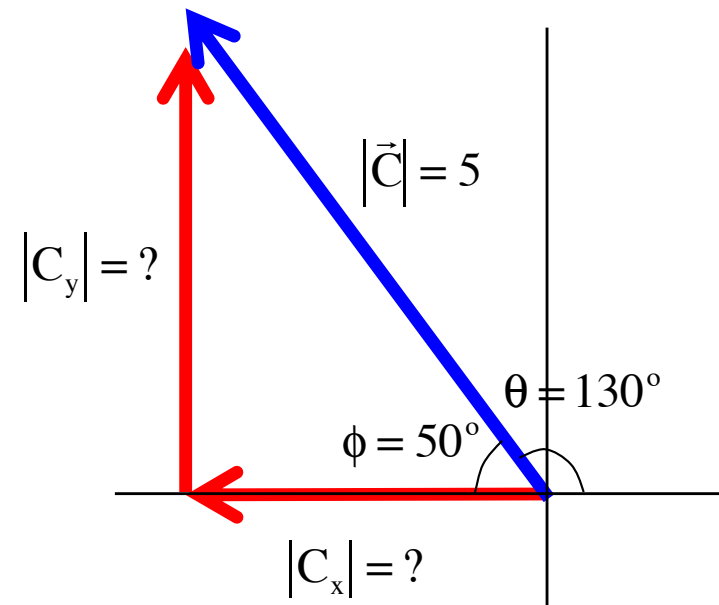
$$\vec{C} = 5 \angle 130^\circ \text{ to unit vector}$$

This is a little bit trickier because you are no longer looking at a first-quadrant triangle. There are two ways to do this. **The easiest is to create a triangle that IS a right triangle** (see sketch), determine its sides, then add whatever signs and unit vectors are needed to characterize the vector. Remember, what you are doing with unit vector notation is creating mini-vectors, one in the x-direction, one in the y-direction, and adding them.



# Vector conversions

$\vec{C} = 5 \angle 130^\circ$  to unit vector



# Vector conversions

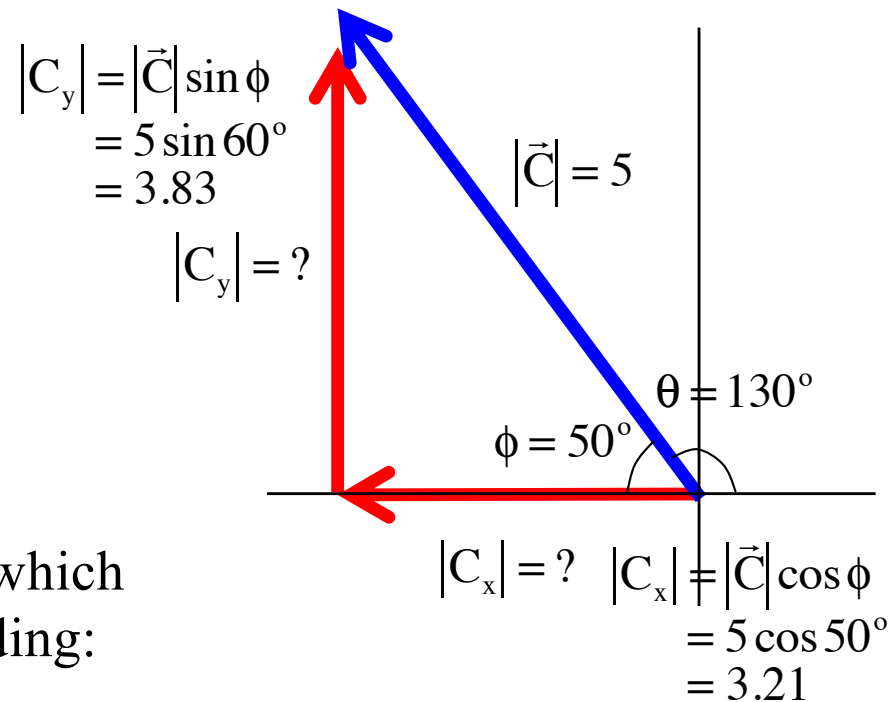
$\vec{C} = 5 \angle 130^\circ$  to unit vector

*In* looking at the sketch, you can either use the magnitudes, which are always positive, and manually put in the signs for the unit vectors, yielding:

$$\begin{aligned}\vec{C} &= |C_x|(\pm\hat{i}) + |C_y|(\pm\hat{j}) \\ &= 3.21(-\hat{i}) + 3.83\hat{j}\end{aligned}$$

OR write it in terms of components, which carry along the signs with them, yielding:

$$\begin{aligned}\vec{C} &= C_x\hat{i} + C_y\hat{j} \\ &= (-3.21)\hat{i} + 3.83\hat{j}\end{aligned}$$



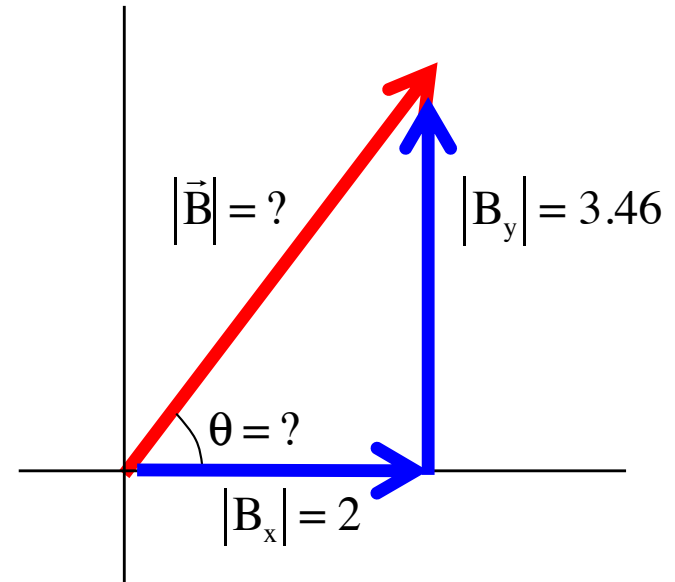
You get the same result either way.

# Vector conversions

- *How* do we go from unit vector to polar notation?
  - Example 1:

$$\vec{B} = 2\hat{i} + 3.46\hat{j} \quad \text{to polar}$$

In looking at the sketch and noting that you can get the magnitude using the Pythagorean relationship and the angle using the *tangent function*, we can write:



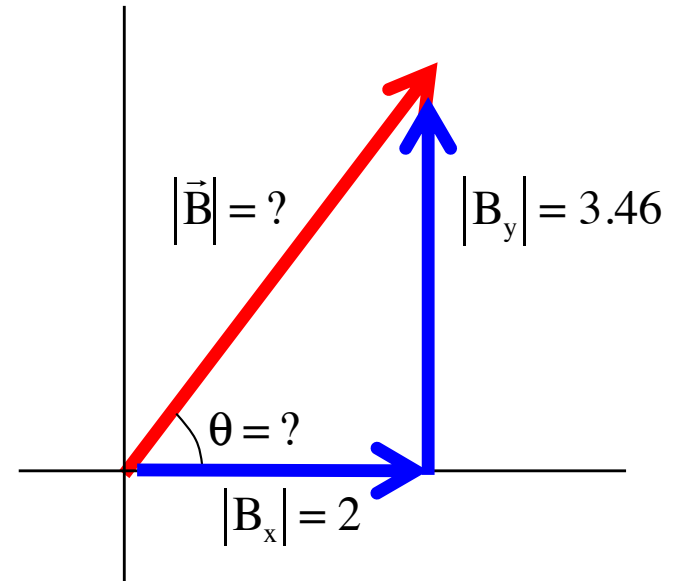
# Vector conversions

- *How* do we go from unit vector to polar notation?

– Example 1:

$$\vec{A} = 2\hat{i} + 3.46\hat{j} \quad \text{to polar}$$

$$\begin{aligned} \vec{A} &= |\vec{A}| \angle \theta \\ &= \left[ (A_x)^2 + (A_y)^2 \right]^{1/2} \angle \tan^{-1} \left( \frac{A_y}{A_x} \right) \\ &= \left[ (2)^2 + (3.46)^2 \right]^{1/2} \angle \tan^{-1} \left( \frac{3.46}{2} \right) \\ &= 4 \angle 60^\circ \end{aligned}$$

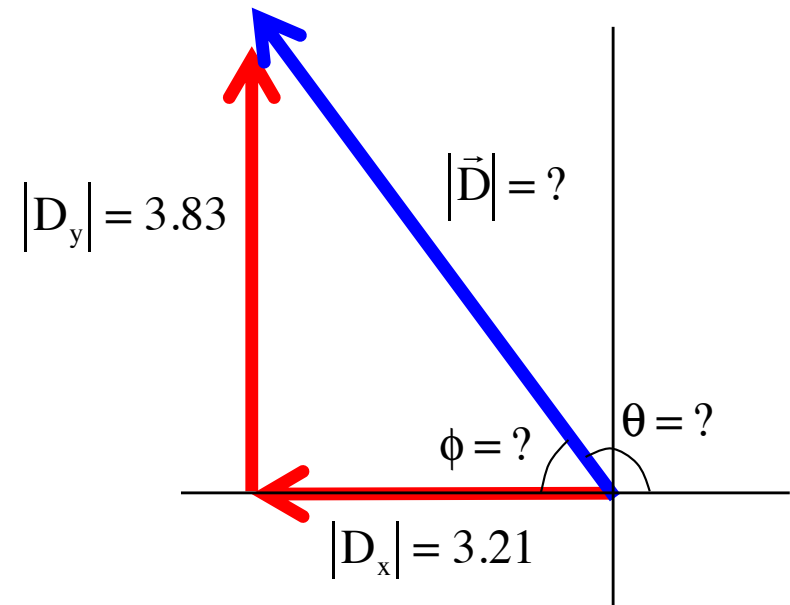


Note that  $|\vec{A}|$  is **ALWAYS** positive.

# Vector conversions

- Example 2:

$$\vec{C} = -3.21\hat{i} + 3.83\hat{j} \text{ to polar}$$



# Vector conversions

- Example 2:

$$\vec{C} = -3.21\hat{i} + 3.83\hat{j} \quad \text{to polar}$$

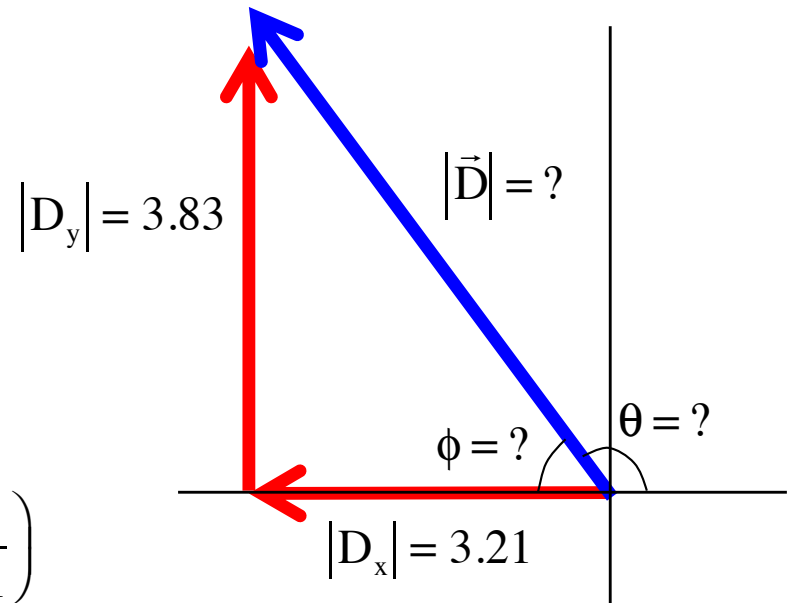
$$\vec{C} = |\vec{C}| \angle \theta$$

$$= \left[ (C_x)^2 + (C_y)^2 \right]^{1/2} \angle \tan^{-1} \left( \frac{C_y}{C_x} \right)$$

$$= \left[ (-3.21)^2 + (3.83)^2 \right]^{1/2} \angle \tan^{-1} \left( \frac{3.83}{-3.21} \right)$$

$= 5 \angle -40^\circ$  except this clearly isn't a fourth quadrant vector, so we need to add  $180^\circ$  to get it into the third quadrant . . .

$$\Rightarrow \vec{C} = 5 \angle (-40^\circ + 180^\circ) = 5 \angle 130^\circ$$





# *Force table mini-lab*

- See the apparatus at the front of the room. As a class, we need to figure out how to balance out the contraption!

# Why bother with vectors?

$0 = -\frac{1}{2}(mv^2) + mg(\Delta y)$   
 $v = \sqrt{2g\Delta y}$

$a = 0 \text{ m/s}^2$   
 $v = 0 \text{ m/s}$

$a = -9.8 \text{ m/s}^2$   
 $v_x = \sqrt{[(ks^2)/m] - 2gs \sin \theta}$

$a = 9.8 \text{ m/s}^2$

$W = 0 = \Delta K + \Delta U_{\text{spring}} + \Delta U_{\text{gravity}}$   
 $0 = (K_f - K_i) + (U_{\text{spring},f} - U_{\text{spring},i}) + (U_{\text{gravity},f} - U_{\text{gravity},i})$   
 $0 = K_f + U_{\text{spring},f} - U_{\text{spring},i}$   
 $0 = \frac{1}{2}mv_f^2 + mgs - \frac{1}{2}ks^2$   
 $v_f = \sqrt{[(ks^2)/m] - 2gs}$

$\tan \theta = v_x/v_y$   
 $\theta = \tan^{-1}(v_x/v_y)$

$y_f = h = s \sin \theta$

HIGHSCORE: 118800  
 SCORE: 0

Image Source:  
<http://www.motivateplay.com>